Shuijing Liu

Postdoctoral Scholar

Computer Science

The University of Texas at Austin

Research interests: Learning-based Robotics, Human-Robot Interaction, Machine Learning

Contact

Email: sliu105@illinois.edu

Website: https://shuijing725.github.io

Google Scholar: https://scholar.google.com/citations?user=I4k7ukgAAAAJ

Education

University of Illinois at Urbana-Champaign

2018 - 2024

Ph.D. in Electrical and Computer Engineering

 $Advisor: Prof.\ Katherine\ Driggs-Campbell$

Thesis: Learning Structured Interaction Models for Robot Navigation in Human Environments

University of Illinois at Urbana-Champaign

2014 - 2018

B.S. in Computer Engineering, minor in Art and Design (Graduated with Highest Honor)

Undergraduate Thesis: Prostate Cancer Diagnosis with Deep Learning

Appointments

The University of Texas at Austin

09/15/2024 - current

Postdoctoral scholar with Yuke Zhu

Publications

*, † indicate equal contributions

- DRAGON: A Dialogue-Based Robot for Assistive Navigation with Visual Language Grounding S. Liu, A. Hasan, K. Hong, R. Wang, P. Chang, Z. Mizrachi, J. Lin, D. L. McPherson, W. A. Rogers, and K. Driggs-Campbell.
 - In Robotics and Automation Letters (RA-L), 2024.
- 2. Predicting Object Interactions with Behavior Primitives: An Application in Stowing Tasks H. Chen, Y. Niu, K. Hong, S. Liu, Y. Wang, Y. Li, and K. Driggs-Campbell. In Conference on Robot Learning (CoRL), 2023. (Best Paper/Student Paper Award Finalist)
- 3. A Data-Efficient Visual-Audio Representation with Intuitive Fine-tuning for Voice-Controlled Robots
 - P. Chang, S. Liu, T. Ji, N. Chakraborty, K. Hong, and K. Driggs-Campbell. In Conference on Robot Learning (CoRL), 2023.
- 4. Structural Attention-Based Recurrent Variational Autoencoder for Highway Vehicle Anomaly Detection
 - N. Chakraborty, A. Hasan*, **S. Liu*,** T. Ji*, W. Liang, D. L. McPherson, and K. Driggs-Campbell. In International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2023.
- 5. Intention Aware Robot Crowd Navigation with Attention-Based Interaction Graph S. Liu, P. Chang, Z. Huang, N. Chakraborty, W. Liang, J. Geng, and K. Driggs-Campbell.

In IEEE International Conference on Robotics and Automation (ICRA), 2023. (Best poster award at the IROS 2023 Last-Mile Robotics Workshop)

6. Occlusion-Aware Crowd Navigation Using People as Sensors

Y. J. Mun, M. Itkina, S. Liu, and K. Driggs-Campbell.

In IEEE International Conference on Robotics and Automation (ICRA), 2023.

7. Learning Visual-Audio Representations for Voice-Controlled Robots

P. Chang, S. Liu, and K. Driggs-Campbell.

In IEEE International Conference on Robotics and Automation (ICRA), 2023.

8. Learning to Navigate Intersections with Unsupervised Driver Trait Inference

S. Liu, P. Chang, H. Chen, N. Chakraborty, and K. Driggs-Campbell.

In International Conference on Robotics and Automation (ICRA), 2022.

9. Off Environment Evaluation Using Convex Risk Minimization

P. Katdare, S. Liu, and K. Driggs-Campbell.

In International Conference on Robotics and Automation (ICRA), 2022.

10. Combining Model-Based Controllers and Generative Adversarial Imitation Learning for Traffic Simulation

H. Chen, T. Ji, S. Liu, and K. Driggs-Campbell.

In IEEE International Conference on Intelligent Transportation Systems (ITSC), 2022.

11. An Interdisciplinary Approach: Potential for Robotic Support to Address Wayfinding Barriers Among Persons with Visual Impairments

M. A. Bayles, T. Kadylak, S. Liu, A. Hasan, W. Liang, K. Hong, K. Driggs-Campbell, and W. A. Rogers

In Human Factors and Ergonomics Society Annual Meeting (HFES), 2022.

12. Decentralized Structural-RNN for Robot Crowd Navigation with Deep Reinforcement Learning

S. Liu*, P. Chang*, W. Liang†, N. Chakraborty†, and K. Driggs-Campbell.

In IEEE International Conference on Robotics and Automation (ICRA), 2021.

13. Robot Sound Interpretation: Combining Sight and Sound in Learning-based Control

P Chang, S Liu, H Chen, and K Driggs-Campbell.

In IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2020.

14. Robust Deep Reinforcement Learning with Adversarial Attacks

A. Pattanaik, Z. Tang*, S. Liu*, G. Bommannan, and G. Chowdhary.

In International Conference on Autonomous Agents and Multiagent Systems (Extended Abstract), 2018.

Honors and Awards

•	Rising Stars in EECS	2024
•	Best Student Paper Award Finalist at CoRL 2023	2023
•	Best poster award at the IROS 2023 Last-Mile Robotics Workshop	2023
•	Conference Travel Award, ECE department at UIUC	2022
•	Honorable mention for TechSAge Stretch Robot Pitch Competition	2021
•	Lauren Kelley Memorial Scholarship	2017 - 2018
•	Professor N. Narayana Rao Scholarship	2016
•	Oakley Scholarship	2015
•	Dean's List, ECE department at UIUC	2014 - 2016

Invited Talks

• Learning Structured Interaction Models for Robot Navigation in Human Environments

RobotiXX Lab, George Mason University, 2024.

Stanford Intelligent Systems Laboratory (SISL), 2024.

• Robot Learning to Interact in Human Spaces

UT Austin Robot Perception and Learning Lab, 2024.

Stanford Vision and Learning Lab (SVL), 2024.

- A Dialogue-Based Robot for Assistive Navigation with Visual Language Grounding CSL Student Conference, 2024.
- Intelligent Robot Crowd Navigation Shuzihuanyu Lecture Series, 2023.
- Pedestrian Trajectory Prediction Meets Social Robot Navigation

Robotics Seminar at Illinois, 2022.

• Robot Learning Through Interactions with Humans Robotics Seminar at Illinois, 2021.

Academic Service

Students mentored

- Changyeon Kim: Ph.D. student in KAIST, visiting scholar in UT Austin.
- Haonan Chen: Ph.D. student in UIUC.
- Kaiwen Hong: Ph.D. student in UIUC.
- Neeloy Chakraborty: B.S. Computer Engineering 2021, now Ph.D. student in UIUC.
- <u>Eric (Weihang) Liang</u>: M.S. Electrical and Computer Engineering, now at Tesla.
- <u>Simon (Haochen) Xia</u>: B.S. Computer Engineering 2026.
- <u>Jerry (Ruoxuan) Wang</u>: B.S. Computer Engineering 2024.
- Justin Lin: B.S. Computer Engineering 2023, now Master student in UIUC.
- Zachary Mizrachi: B.S. Computer Engineering 2024.

Reviews

- Journal reviews: <u>IEEE T-RO</u>, <u>IEEE RA-L</u>, <u>SAGE IJRR</u>, <u>IEEE TAI</u>
- Conference reviews: RSS, ICRA, IROS, CoRL, Humanoids

Teaching

Graduate Teaching Assistant

- ECE 598: Human-Centered Robotics (Fall 2020)
- ECE 470: Introduction to Robotics (Fall 2019 Spring 2020)
- ECE 120: Introduction to Computing (Fall 2018 Spring 2019)

Undergraduate Course Assistant

• ECE 110: Introduction to Electronics (Fall 2016 - Spring 2018)

Industry Experience

• Research Scientist Internship, Bosch Center for Artificial Intelligence

Summer 2023

• Applied Scientist Internship, Robotics & AI, Amazon

Summer 2022

References

• Katherine Driggs-Campbell, Assistant Professor in ECE department at UIUC

Email: krdc@illinois.edu

• Yuke Zhu, Assistant Professor in CS department at UT Austin

Email: yukez@cs.utexas.edu

• Nancy M. Amato, Abel Bliss Professor of Engineering and Department Head in CS department at UIUC

Email: namato@illinois.edu

• Kris Hauser, Professor in CS department at UIUC

Email: kkhauser@illinois.edu

• Junyi Geng, Assistant Professor in Aerospace Engineering department at The Pennsylvania State University

Email: jgeng@psu.edu